

Existence results for nonlinear anisotropic elliptic partial differential equations with variable exponents

Mokhtar Naciri 

Abstract. The focus of this paper will be on studying the existence of solutions in the sense of distribution, for a class of nonlinear partial differential equations defined by a variable exponent anisotropic elliptic operator with a growth conditions given by a strictly positive continuous real function. The functional setting involves variable exponents anisotropic Sobolev spaces.

Mathematics Subject Classification (2010): 35J60, 35J66, 35J67.

Keywords: Nonlinear elliptic problem, growth conditions, anisotropic sobolev spaces, variable exponents, distributional solution, existence.

1. Introduction

Our goal is to prove the existence of at least one distributional solution to the $\vec{p}(\cdot)$ –nonlinear elliptic partial differential equations of the type :

$$\begin{cases} -\sum_{i=1}^N \partial_i(\sigma_i(x, u, \partial_i u)) + g(x, u) = f, & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (1.1)$$

Where, $\Omega \subset \mathbb{R}^N$ ($N \geq 2$) is a bounded open set with Lipschitz boundary $\partial\Omega$, $f \in L^{\vec{p}(\cdot)}(\Omega) (= \bigcap_{i=1}^N L^{p'_i(\cdot)}(\Omega))$, with $p'_i(\cdot) (= \frac{p_i}{p_i-1}, i = 1, \dots, N)$ denotes the Hölder conjugate of $p_i(\cdot)$, $\sigma_i : \Omega \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$, $i = 1, \dots, N$, are Carathéodory functions

Received 28 January 2025; Accepted 10 June 2025.

© Studia UBB MATHEMATICA. Published by Babeş-Bolyai University

 This work is licensed under a Creative Commons Attribution-NonCommercial-NoDerivatives 4.0 International License.

fulfilling for almost everywhere $x \in \Omega$ and every $s, \eta, \eta' \in \mathbb{R}$, $(\eta, \eta') \neq (0, 0)$, the following :

$$|\sigma_i(x, s, \eta)| \leq c_1 K(|s|)(|\eta| + |\vartheta_i|)^{p_i(x)-1}, \quad (1.2)$$

$$\sigma_i(x, s, \eta)\eta \geq c_2 K(|s|)|\eta|^{p_i(x)}, \quad (1.3)$$

$$(\sigma_i(x, s, \eta) - \sigma_i(x, s, \eta'))(\eta - \eta') \geq \Theta_i(x, \eta, \eta'), \quad (1.4)$$

$$\Theta_i(x, \eta, \eta') = \begin{cases} c_3 |\eta - \eta'|^{p_i(x)}, & \text{if } p_i(x) \geq 2 \\ c_4 \frac{|\eta - \eta'|^2}{(|\eta| + |\eta'|)^{2-p_i(x)}}, & \text{if } 1 < p_i(x) < 2 \end{cases}$$

where, c_l , $l = 1, \dots, 4$ are positive constants, $\vartheta_i \in L^{p_i(\cdot)}(\Omega)$, $i = 1, \dots, N$, and $K(\cdot) : \mathbb{R}_+ \rightarrow \mathbb{R}_+^*$ is a continuous function such that,

$$K(|\xi|) \geq \alpha |\xi|^{r(x)}, \quad \text{for all } |\xi| \geq \lambda, \quad (1.5)$$

with, $\alpha > 0$, $\lambda > 0$ and $r(\cdot) \in \mathcal{C}(\overline{\Omega})$, where $r(\cdot) > 0$ in $\overline{\Omega}$.

For some $\beta > 0$

$$K(|s|) \geq \beta, \quad \text{for all } s \in \mathbb{R}. \quad (1.6)$$

$g : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a Carathéodory function and satisfies ;

a.e. $x \in \Omega$ the following conditions:

$$g(x, s)(s - s') \geq 0, \quad \forall s, s' \in \mathbb{R}, |s| = |s'|, \quad (1.7)$$

$$\sup_{|s| \leq t} |g(x, s)| \in L^1(\Omega), \quad \forall s \in \mathbb{R} \text{ and } \forall t > 0, \quad (1.8)$$

$$|g(x, s)| \leq c \sum_{i=1}^N |s|^{p_i(x)-1}, \quad \forall s \in \mathbb{R}. \quad (1.9)$$

As a typical example, we can consider the following model equation

$$(\sigma_i(x, u, \partial_i u) = K(|u|)|\partial_i u|^{p_i(x)-2} \partial_i u, g(x, u) = u \sum_{i=1}^N |u|^{p_i(x)-2}):$$

$$\begin{cases} - \sum_{i=1}^N \partial_i (K(|u|)|\partial_i u|^{p_i(x)-2} \partial_i u) + u \sum_{i=1}^N |u|^{p_i(x)-2} = f(x), & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \end{cases}$$

where $f \in L^{\vec{p}(\cdot)}(\Omega)$, and the continuous function $K(\cdot)$ is defined for any fixed $x \in \Omega$ as follows:

$$\forall \eta \geq 0 : K(\eta) = \begin{cases} 1 + \lambda^{r(x)}, & \text{if } \eta < \lambda, \\ 1 + \eta^{r(x)}, & \text{if } \eta \geq \lambda, \end{cases}$$

where $\lambda > 0$, and $r(\cdot) \in \mathcal{C}(\overline{\Omega})$ with $r(\cdot) > 0$ in $\overline{\Omega}$.

Our boundary-value problems entails an $\vec{p}(x)$ -nonlinear elliptic differential operator wherein those sorts of operators have many makes use of within the carried out discipline of diverse sciences, amongst them modeling of image processing and electro-rheological fluids (see [9, 21, 3]). From the theoretical side related to the existence of solutions, we can refer, without limitation, to [11, 12, 13, 10, 14, 15, 16, 17, 18, 19, 20].

This paper seeks to prove the existence results of ditributional solutions for a class of anisotropic nonlinear elliptic problems with variable exponents and growth conditions given by a real positive continuous function, will provide us regular solutions in the anisotropic space $W_0^{1,\vec{q}(\cdot)}(\Omega)$ such that, $\vec{q}(\cdot) = (q_1(\cdot), \dots, q_N(\cdot))$, be restricted as in Theorem 3.2.

The proof of our main result requires proving the existence of a sequence of suitable approximate solutions (u_n) by applying the main Theorem of pseudo-monotone operators and the results obtained in [12, 13]. Prior estimates are then used to show the boundedness of the solutions u_n and the almost everywhere convergence of their partial derivatives $\partial_i u_n$, $i = 1, \dots, N$, which can be converted into strong L^1 -convergence. Through this, we can pass to the limit by L^1 -strongly sense for $\sigma_i(x, T_n(u_n), \partial_i u_n)$, and for $g(x, u_n)$, then we conclude the convergence of u_n to the solution of (1.1).

The paper is divided into several sections, in Section 2 we discuss variable exponents anisotropic Lebesgue-Sobolev spaces and their key characteristics, as well as mentioning some embedding theorems. The main theorem and its proof can be found in Section 3.

2. Preliminaries and basic concepts

In this section, we will learn about anisotropic Lebesgue-Sobolev spaces with variable exponent and their most important distinctive properties, as explained, for example, in the papers [6, 4, 5].

Let $\Omega \subset \mathbb{R}^N$ ($N \geq 2$) is a bounded open subset, and let the following set be:

$$\mathcal{C}_+(\overline{\Omega}) = \{\text{continuous function } p(\cdot) : \overline{\Omega} \mapsto \mathbb{R}, \quad p^- (= \min_{x \in \overline{\Omega}} p(x)) > 1\}.$$

Assume $p(\cdot) \in \mathcal{C}_+(\overline{\Omega})$. The variable exponent Lebesgue reflexive Banach space $(L^{p(\cdot)}(\Omega), \|\cdot\|_{p(\cdot)})$ defined by

$$L^{p(\cdot)}(\Omega) := \{\text{measurable functions } u : \Omega \mapsto \mathbb{R}, \int_{\Omega} |u(x)|^{p(x)} dx < \infty\},$$

under the Luxemburg norm

$$u \mapsto \|u\|_{p(\cdot)} := \|u\|_{L^{p(\cdot)}(\Omega)} = \inf \left\{ s > 0 : \varrho_{p(\cdot)}\left(\frac{u}{s}\right) \leq 1 \right\}.$$

The function

$$\varrho_{p(\cdot)} : u \mapsto \int_{\Omega} |u(x)|^{p(x)} dx \text{ is called the convex modular.}$$

The variable exponents Sobolev Banach space $(W^{1,p(\cdot)}(\Omega), \|\cdot\|_{1,p(\cdot)})$ defined as fellows

$$W^{1,p(\cdot)}(\Omega) := \left\{ u \in L^{p(\cdot)}(\Omega) : |\nabla u| \in L^{p(\cdot)}(\Omega) \right\},$$

such that

$$u \mapsto \|u\|_{1,p(\cdot)} := \|\nabla u\|_{p(\cdot)}. \quad (2.1)$$

We define also the reflexive and separable Banach space $\left(W_0^{1,p(\cdot)}(\Omega), \|\cdot\|_{1,p(\cdot)}\right)$ by

$$W_0^{1,p(\cdot)}(\Omega) := \overline{C_0^\infty(\Omega)}^{W^{1,p(\cdot)}(\Omega)}.$$

The following Hölder type inequality holds :

$$\left| \int_{\Omega} uv \, dx \right| \leq \left(\frac{1}{p^-} + \frac{1}{p'^-} \right) \|u\|_{p(\cdot)} \|v\|_{p'(\cdot)} \leq 2 \|u\|_{p(\cdot)} \|v\|_{p'(\cdot)},$$

where, $p'(\cdot)$ denotes the Hölder conjugate of $p(\cdot)$ (i.e. $\frac{1}{p(\cdot)} + \frac{1}{p'(\cdot)} = 1$ in $\overline{\Omega}$).

Next results(see [4, 5]) we need to use them later. Let $u \in L^{p(\cdot)}(\Omega)$, then:

$$\min \left(\varrho_{p(\cdot)}^{\frac{1}{p^+}}(u), \varrho_{p(\cdot)}^{\frac{1}{p^-}}(u) \right) \leq \|u\|_{p(\cdot)} \leq \max \left(\varrho_{p(\cdot)}^{\frac{1}{p^+}}(u), \varrho_{p(\cdot)}^{\frac{1}{p^-}}(u) \right), \quad (2.2)$$

$$\min \left(\|u\|_{p(\cdot)}^-, \|u\|_{p(\cdot)}^+ \right) \leq \varrho_{p(\cdot)}(u) \leq \max \left(\|u\|_{p(\cdot)}^-, \|u\|_{p(\cdot)}^+ \right). \quad (2.3)$$

We will now define the variable exponents anisotropic Sobolev spaces $W^{1,\vec{p}(\cdot)}(\Omega)$.

Let $p_i(\cdot) \in C(\overline{\Omega}, [1, +\infty))$, $i \in \{1, \dots, N\}$, and $\forall x \in \overline{\Omega}$ we set that

$$\vec{p}(x) = (p_1(x), \dots, p_N(x)), \quad p_+(x) = \max_{1 \leq i \leq N} p_i(x), \quad p_-(x) = \min_{1 \leq i \leq N} p_i(x),$$

$$\frac{1}{\bar{p}(x)} = \frac{1}{N} \sum_{i=1}^N \frac{1}{p_i(x)}.$$

The Banach space $W^{1,\vec{p}(\cdot)}(\Omega)$ is defined by

$$W^{1,\vec{p}(\cdot)}(\Omega) = \left\{ u \in L^{p_+(\cdot)}(\Omega) \text{ and } \partial_i u \in L^{p_i(\cdot)}(\Omega), \quad i \in \{1, \dots, N\} \right\},$$

equipped with the following norm :

$$u \mapsto \|u\|_{\vec{p}(\cdot)} = \|u\|_{p_+(\cdot)} + \sum_{i=1}^N \|\partial_i u\|_{p_i(\cdot)}. \quad (2.4)$$

The Banach space $\left(W_0^{1,\vec{p}(\cdot)}(\Omega), \|\cdot\|_{\vec{p}(\cdot)}\right)$ defined as follows

$$W_0^{1,\vec{p}(\cdot)}(\Omega) = \overline{C_0^\infty(\Omega)}^{W^{1,\vec{p}(\cdot)}(\Omega)},$$

Let $p(\cdot) \in C_+(\overline{\Omega})$, the variable exponent Marcinkiewicz space $\mathcal{M}^{p(\cdot)}(\Omega)$ is defined by

$$\mathcal{M}^{p(\cdot)}(\Omega) := \{ \text{measurable functions } u : \Omega \mapsto \mathbb{R};$$

$$\exists M > 0 : \int_{\{|u|>s\}} t^{p(x)} \, dx \leq M, \quad \forall s > 0 \}.$$

The truncation function $\forall t > 0$, $T_t : \mathbb{R} \longrightarrow \mathbb{R}$ is defined as

$$T_t(s) := \begin{cases} s, & \text{if } |s| \leq t, \\ \frac{s}{|s|}t, & \text{if } |s| > t, \end{cases} \quad (2.5)$$

and its derivative (see [11]) given by

$$(DT_t)(s) = \begin{cases} 1, & |s| < t, \\ 0, & |s| > t. \end{cases} \quad (2.6)$$

3. Statement of results and proof

Definition 3.1. The function $u : \Omega \rightarrow \mathbb{R}$ is a distributional solution for (1.1) if and only if $u \in W_0^{1,1}(\Omega)$, and $\forall \varphi \in C_c^\infty(\Omega)$:

$$\int_{\Omega} \sum_{i=1}^N \sigma_i(x, u, \partial_i u) \partial_i \varphi \, dx + \int_{\Omega} g(x, u) \varphi \, dx = \int_{\Omega} f(x) \varphi \, dx.$$

The main result is that.

Theorem 3.2. Let $p_i(\cdot) \in C(\overline{\Omega}, [1, +\infty))$, $i = 1, \dots, N$, such that $\bar{p} < N$. Assume that $f \in L^{\vec{p}(\cdot)}(\Omega)$, and g, σ_i , $i = 1, \dots, N$, be Carathéodory functions that satisfy (1.2)-(1.4), and (1.7)-(1.9). If we have

$$\frac{\bar{p}(\cdot)(N-1)}{N(r(\cdot)+1)(\bar{p}(\cdot)-1)} < p_i(\cdot) < \frac{\bar{p}(\cdot)(N-1)}{(r(\cdot)+1)(N-\bar{p}(\cdot))}, \text{ in } \overline{\Omega}, \quad i = 1, \dots, N \quad (3.1)$$

where, $r(\cdot)$ defined in (1.5) and satisfies

$$r(\cdot) < \frac{N - \bar{p}(\cdot)}{N(\bar{p}(\cdot) - 1)} \text{ in } \overline{\Omega}. \quad (3.2)$$

Then (1.1) has at least one solution u in the sense of distributions in $W_0^{1, \vec{q}(\cdot)}(\Omega)$, where $\vec{q}(\cdot) = (q_1(\cdot), \dots, q_N(\cdot))$, and

$$\max\{1, (r(\cdot)+1)p_i(\cdot)-1\} < q_i(\cdot) < \frac{Np_i(\cdot)(\bar{p}(\cdot)-1)(r(\cdot)+1)}{\bar{p}(\cdot)(N-1)} \text{ in } \overline{\Omega}, \quad i = 1, \dots, N. \quad (3.3)$$

Remark 3.3. The assumption (3.2) ensure that

$$\frac{\bar{p}(\cdot)(N-1)}{N(r(\cdot)+1)(\bar{p}(\cdot)-1)} > 1 \text{ in } \overline{\Omega}, \quad i = 1, \dots, N.$$

Remark 3.4. The upper bound in (3.1) implies that

$$\frac{Np_i(\cdot)(\bar{p}(\cdot)-1)(r(\cdot)+1)}{\bar{p}(\cdot)(N-1)} > (r(\cdot)+1)p_i(\cdot)-1 \text{ in } \overline{\Omega}, \quad i = 1, \dots, N. \quad (3.4)$$

3.1. Existence of approximate solutions

Let (f_n) be a sequence of bounded functions defined in Ω which converges to f in $L^{\vec{p}(\cdot)}(\Omega)$.

It should be noted here that:

Since $f_n \in L^{\vec{p}(\cdot)}(\Omega)$, then from (2.2), we obtain

$$\|f_n\|_{p'_i(\cdot)} \leq 1 + \rho_{p'_i(\cdot)}^{\frac{1}{p'_i(\cdot)}}(f_n) \leq 2 + \rho_{p_i(\cdot)}^{\frac{1}{p_i(\cdot)}}(f_n) < \infty.$$

Through this, we conclude that

$$f_n \text{ is bounded in } L^{p'_i(\cdot)}(\Omega), \quad i = 1, \dots, N. \quad (3.5)$$

Lemma 3.5. *Let $p_i(\cdot) \in C(\overline{\Omega},]1, +\infty))$, $i = 1, \dots, N$, such that $\bar{p} < N$, and let f is in $L^{\vec{p}(\cdot)}(\Omega)$. Let g, σ_i , $i = 1, \dots, N$, be Carathéodory functions satisfying (1.2)-(1.4), and (1.7)-(1.9). Then, there exists at least one weak solution $u_n \in W_0^{1, \vec{p}(\cdot)}(\Omega)$ to the approximated problems*

$$\begin{aligned} - \sum_{i=1}^N \partial_i (\sigma_i(x, T_n(u_n)), \partial_i u_n) + g(x, u_n) &= f_n, \quad \text{in } \Omega, \\ u_n &= 0, \quad \text{on } \partial\Omega, \end{aligned} \quad (3.6)$$

in the sense that; for every $\varphi \in W_0^{1, \vec{p}(\cdot)}(\Omega) \cap L^\infty(\Omega)$

$$\sum_{i=1}^N \int_{\Omega} \sigma_i(x, T_n(u_n), \partial_i u_n) \partial_i \varphi \, dx + \int_{\Omega} g(x, u_n) \varphi \, dx = \int_{\Omega} f_n \varphi \, dx. \quad (3.7)$$

Proof. Consider the problem

$$\begin{aligned} - \sum_{i=1}^N \partial_i (\sigma_i(x, T_n(u_{n_k}), \partial_i u_{n_k})) + g_k(x, u_{n_k}) &= f_n, \quad \text{in } \Omega, \\ u_{n_k} &= 0, \quad \text{on } \partial\Omega, \end{aligned} \quad (3.8)$$

where,

$$g_k(x, \xi) = \frac{g(x, \xi)}{1 + \frac{|g(x, \xi)|}{k}}, \quad \forall k \in \mathbb{N}^*.$$

Note that,

$$|g_k(x, \xi)| \leq |g(x, \xi)|, \quad \text{and} \quad |g_k(x, \xi)| \leq k.$$

In a similar manner to the results obtained in [12] or in [13] by applying the main Theorem on pseudo-monotone operators, we conclude that there exists a solution $u_{n_k} \in W_0^{1, \vec{p}(\cdot)}(\Omega)$ to problem (3.8), which satisfies

$$\begin{aligned} \sum_{i=1}^N \int_{\Omega} \sigma_i(x, T_n(u_{n_k}), \partial_i u_{n_k}) \partial_i \varphi \, dx + \int_{\Omega} g_k(x, u_{n_k}) \varphi \, dx \\ = \int_{\Omega} f_n \varphi \, dx, \quad \forall \varphi \in W_0^{1, \vec{p}(\cdot)}(\Omega), \end{aligned} \quad (3.9)$$

And also in a similar way, we can obtain (3.7) by passing to the limit in (3.9). $\square$

3.1.1. A priori estimates.

Lemma 3.6. *Let $u_n \in W_0^{1, \vec{p}(\cdot)}(\Omega) \cap L^\infty(\Omega)$ be a solution to problem (3.6). Then, there exists a constant C , such that*

$$\sum_{i=1}^N \int_{\{|u_n| \leq t\}} |\partial_i u_n|^{p_i(x)} \, dx \leq C(t+1), \quad \forall t > 0, \quad (3.10)$$

$$\int_{\Omega} |g(x, u_n)| \, dx \leq C, \quad (3.11)$$

$$\sum_{i=1}^N \int_{\{K(|u_n|) < t\}} (t+1)^{-1} |\partial_i(K(|u_n|))|^{p_i(x)} \, dx \leq C, \quad \forall t > 0. \quad (3.12)$$

Proof. By choosing $\varphi = T_t(u_n)$ in (3.7) and use (1.3), (1.6), (2.5), and (2.6), we find that, for all $t > 0$

$$\begin{aligned} C \sum_{i=1}^N \int_{|u_n| \leq t} |\partial_i u_n|^{p_i(x)} \, dx + t \int_{|u_n| > t} \frac{u_n}{|u_n|} g(x, u_n) \, dx \\ \leq ct + \int_{|u_n| < t} |u_n| |g(x, u_n)| \, dx. \end{aligned} \quad (3.13)$$

Then, from (1.8), and the fact that

$$\frac{u_n}{|u_n|} g(x, u_n) \geq |g(x, u_n)|. \quad (3.14)$$

Which is produced by the following: due (1.7) we get

$\frac{u_n}{|u_n|} g(x, u_n) - |g(x, u_n)| = \frac{1}{|u_n|} g(x, u_n) (u_n - |u_n| \frac{g(x, u_n)}{|g(x, u_n)|}) \geq 0$, we obtain

$$C \sum_{i=1}^N \int_{|u_n| \leq t} |\partial_i u_n|^{p_i(x)} \, dx + t \int_{|u_n| > t} |g(x, u_n)| \, dx \leq c't. \quad (3.15)$$

So, (3.15) give us (3.10), and also, for all $t > 0$

$$\int_{|u_n| > t} |g(x, u_n)| \, dx \leq c'. \quad (3.16)$$

From (3.16) and (1.8) we get (3.11).

In order to prove (3.12), we choose $\varphi = T_t(K(|u_n|))$ in (3.7) with the use of (1.3), (1.6), (2.5), and (2.6), we can get for all $t > 0$

$$\begin{aligned} c_2 \beta \sum_{i=1}^N \int_{\{K(|u_n|) < t\}} |\partial_i(K(|u_n|))|^{p_i(x)} \, dx + t \int_{K(|u_n|) > t} g(x, u_n) \, dx \\ + \beta \int_{K(|u_n|) \leq t} g(x, u_n) \, dx \leq ct. \end{aligned} \quad (3.17)$$

Then, we get

$$\begin{aligned} c_2 \beta \sum_{i=1}^N \int_{\{K(|u_n|) < t\}} |\partial_i(K(|u_n|))|^{p_i(x)} \, dx \\ \leq ct + t \int_{\{K(|u_n|) > t\}} |g(x, u_n)| \, dx + \beta \int_{\{K(|u_n|) \leq t\}} |g(x, u_n)| \, dx. \end{aligned} \quad (3.18)$$

Let's simplify the second side to (3.18).

By (1.8) and (3.16), we obtain

$$\begin{aligned} \int_{\{K(|u_n|)>t\}} |g(x, u_n)| \, dx &= \int_{\{K(|u_n|)>t\} \cap \{|u_n|>t\}} |g(x, u_n)| \, dx \\ &+ \int_{\{K(|u_n|)>t\} \cap \{|u_n|\leq t\}} |g(x, u_n)| \, dx \\ &\leq \int_{\{|u_n|>t\}} |g(x, u_n)| \, dx + \int_{\{|u_n|\leq t\}} |g(x, u_n)| \, dx \leq C, \end{aligned}$$

and

$$\begin{aligned} \int_{\{K(|u_n|)<t\}} |g(x, u_n)| \, dx &= \int_{\{K(|u_n|)<t\} \cap \{|u_n|>t\}} |g(x, u_n)| \, dx \\ &+ \int_{\{K(|u_n|)<t\} \cap \{|u_n|\leq t\}} |g(x, u_n)| \, dx \\ &\leq \int_{\{|u_n|>t\}} |g(x, u_n)| \, dx + \int_{\{|u_n|\leq t\}} |g(x, u_n)| \, dx \leq C'. \end{aligned}$$

Through this we find that, (3.18) gives us

$$\sum_{i=1}^N \int_{\{K(|u_n|)<t\}} |\partial_i(K(|u_n|))|^{p_i(x)} \, dx \leq c(t+1). \quad (3.19)$$

Then, from (3.17) we obtain (3.12). $\square$

Remark 3.7. (3.10) implies that

$$\int_{\{|u_n|\leq t\}} (t+1)^{-1} |\partial_i u_n|^{p_i(x)} \, dx \leq C, \quad \forall t > 0. \quad (3.20)$$

Remark 3.8. The relationship (3.14) implies that

$$u_n g(x, u_n) \geq 0. \quad (3.21)$$

We need the following technical Lemma that came in [11] and scalar case in [2]

Lemma 3.9. (see [2, 11]) Let $\vec{p}(\cdot) = (p_1(\cdot), \dots, p_N(\cdot)) \in (C_+(\bar{\Omega}))^N$ with $\bar{p}(\cdot) < N$, and let f be a nonnegative function in $W_0^{1, \vec{p}(\cdot)}(\Omega)$. Suppose that there exists a constant c such that

$$\sum_{i=1}^N \int_{\{f \leq t\}} |\partial_i f|^{p_i(x)} \, dx \leq c(t+1), \quad \forall t > 0. \quad (3.22)$$

Then there exists a constant C , depending on c , such that

$$\int_{\{f > t\}} t^{h(x)} \, dx \leq C, \quad \forall t > 0, \quad h(x) = \frac{N(\bar{p}(x) - 1)}{N - \bar{p}(x)}, \quad \forall x \in \bar{\Omega}. \quad (3.23)$$

Lemma 3.10. *Let $u_n \in W_0^{1, \vec{p}(\cdot)}(\Omega) \cap L^\infty(\Omega)$ be a solution to problem (3.6). Then,*

$$\partial_i(K(|u_n|)) \text{ is bounded in } \mathcal{M}^{\frac{Np_i(\cdot)(\vec{p}(\cdot)-1)}{\vec{p}(\cdot)(N-1)}}(\Omega), \quad i = 1, \dots, N \quad (3.24)$$

$$\partial_i u_n \text{ is bounded in } \mathcal{M}^{\frac{Np_i(\cdot)(\vec{p}(\cdot)-1)(r(\cdot)+1)}{\vec{p}(\cdot)(N-1)}}(\Omega), \quad i = 1, \dots, N. \quad (3.25)$$

Proof. For all $i = 1, \dots, N$ setting $\alpha_i(\cdot) = \frac{p_i(\cdot)}{h(\cdot)+1}$ where $h(x) = \frac{N(\vec{p}(x)-1)}{N-\vec{p}(x)}$, $\forall x \in \bar{\Omega}$, then we have:

If $0 < t < 1$, we have trivially that

$$\int_{\{|\partial_i(K(|u_n|))|^{\alpha_i(x)} > t\}} t^{h(x)} dx \leq |\Omega|.$$

If $t \geq 1$, using (3.12), Lemma 3.9 (due (3.10)), and the fact that $|\partial_i(|u_n|)| \leq |\partial_i u_n|$, $u_n \neq 0$, $i = 1, \dots, N$, we get that

$$\begin{aligned} \int_{\{|\partial_i(K(|u_n|))|^{\alpha_i(x)} > t\}} t^{h(x)} dx &\leq \int_{\{|\partial_i(K(|u_n|))|^{\alpha_i(x)} > t\} \cap \{K(|u_n|) < t\}} t^{h(x)} dx \\ &\quad + \int_{\{|\partial_i(K(|u_n|))|^{\alpha_i(x)} > t\} \cap \{K(|u_n|) \geq t\}} t^{h(x)} dx \\ &\leq \int_{\{|\partial_i(K(|u_n|))|^{\alpha_i(x)} > t\} \cap \{K(|u_n|) < t\} \cap \{|u_n| \leq t\}} t^{h(x)} dx \\ &\quad + \int_{\{|\partial_i(K(|u_n|))|^{\alpha_i(x)} > t\} \cap \{K(|u_n|) < t\} \cap \{|u_n| > t\}} t^{h(x)} dx \\ &\quad + \int_{\{|\partial_i(K(|u_n|))|^{\alpha_i(x)} > t\} \cap \{K(|u_n|) \geq t\} \cap \{|u_n| \leq t\}} t^{h(x)} dx \\ &\quad + \int_{\{|\partial_i(K(|u_n|))|^{\alpha_i(x)} > t\} \cap \{K(|u_n|) \geq t\} \cap \{|u_n| > t\}} t^{h(x)} dx \\ &\leq 2 \int_{\{K(|u_n|) < t\}} t^{h(x)} dx + 2 \int_{\{|u_n| > t\}} t^{h(x)} dx \\ &\leq 2 \int_{\{K(|u_n|) < t\}} t^{h(x)} \left(\frac{|\partial_i(K(|u_n|))|^{\alpha_i(x)}}{t} \right)^{\frac{p_i(x)}{\alpha_i(x)}} dx \\ &\quad + 2 \int_{\{|u_n| > t\}} t^{h(x)} dx \\ &\leq 2 \int_{\{K(|u_n|) < t\}} t^{-1} |\partial_i(K(|u_n|))|^{p_i(x)} dx + c \\ &\leq 4 \int_{\{K(|u_n|) < t\}} (2t)^{-1} |\partial_i(K(|u_n|))|^{p_i(x)} dx + c \\ &\leq 4 \int_{\{K(|u_n|) < t\}} (t+1)^{-1} |\partial_i(K(|u_n|))|^{p_i(x)} dx + c \leq C'. \end{aligned}$$

Then, for all $i = 1, \dots, N$, $|\partial_i(K(|u_n|))|^{|\alpha_i(\cdot)|}$ is bounded in $\mathcal{M}^{h(\cdot)}(\Omega)$.

This gives us, for all $i = 1, \dots, N$, $|\partial_i(K(|u_n|))|$ is bounded in $\mathcal{M}^{h(\cdot)\alpha_i(\cdot)}(\Omega)$ where

$$h(\cdot)\alpha_i(\cdot) = \frac{p_i(\cdot)h(\cdot)}{h(\cdot) + 1} = \frac{Np_i(\cdot)(\bar{p}(\cdot) - 1)}{\bar{p}(\cdot)(N - 1)}.$$

Now we will prove (3.25), For $\alpha_i(\cdot)$, $i = 1, \dots, N$ and $h(\cdot)$ defined previously, we find that

If $0 < t < 1$, we get that

$$\int_{\{||\partial_i u_n||^{|\alpha_i(x)(r(x)+1)|} > t\}} t^{h(x)} dx \leq |\Omega|.$$

If $t \geq 1$, by (3.12), Lemma 3.9 (due (3.10)), and the fact that

$|\partial_i |u_n| | \leq |\partial_i u_n|$, $u_n \neq 0$, $i = 1, \dots, N$, we obtain that

$$\begin{aligned} \int_{\{|\partial_i u_n|^{|\alpha_i(x)(r(x)+1)|} > t\}} t^{h(x)} dx &\leq \int_{\{|\partial_i u_n|^{|\alpha_i(x)(r(x)+1)|} > t\} \cap \{|u_n| \leq t\}} t^{h(x)} dx \\ &\quad + \int_{\{|\partial_i u_n|^{|\alpha_i(x)(r(x)+1)|} > t\} \cap \{|u_n| > t\}} t^{h(x)} dx \\ &\leq \int_{\{|u_n| \leq t\}} t^{h(x)} \left(\frac{|\partial_i u_n|^{|\alpha_i(x)(r(x)+1)|}}{t} \right)^{\frac{p_i(x)}{\alpha_i(x)(r(x)+1)}} dx \\ &\quad + \int_{\{|u_n| > t\}} t^{h(x)} dx \\ &\leq \int_{\{|u_n| \leq t\}} t^{h(x)r(x)-1} |\partial_i u_n|^{p_i(x)} dx + c. \end{aligned} \quad (3.26)$$

By noting that the assumption (3.2) is equivalent to:

$$h(\cdot)r(\cdot) - 1 < 0, \quad \text{in } \bar{\Omega},$$

and through the positivity of $r(\cdot)$ and $h(\cdot)$, we find that

$$h(\cdot)r(\cdot) - 1 \geq -1, \quad \text{in } \bar{\Omega}.$$

So, we get that

$$(h(\cdot)r(\cdot) - 1) \in [-1, 0), \quad \text{in } \bar{\Omega}. \quad (3.27)$$

By using (3.27) in (3.26), and thanks to (3.20), we can obtain that

$$\begin{aligned} \int_{\{|\partial_i u_n|^{|\alpha_i(x)(r(x)+1)|} > t\}} t^{h(x)} dx &\leq \int_{\{|u_n| \leq t\}} t^{-1} |\partial_i u_n|^{p_i(x)} dx + c \\ &\leq 2 \int_{\{|u_n| \leq t\}} (2t)^{-1} |\partial_i u_n|^{p_i(x)} dx + c \\ &\leq 2 \int_{\{|u_n| \leq t\}} (t+1)^{-1} |\partial_i u_n|^{p_i(x)} dx + c \leq C. \end{aligned} \quad (3.28)$$

Hence, we can obtain,

$$|\partial_i u_n|^{|\alpha_i(\cdot)(r(x)+1)|} \text{ is bounded in } \mathcal{M}^{h(\cdot)}(\Omega) \quad i = 1, \dots, N.$$

From this we conclude that

$$|\partial_i u_n| \text{ is bounded in } \mathcal{M}^{h(\cdot)\alpha_i(\cdot)(r(\cdot)+1)}(\Omega) \quad i = 1, \dots, N,$$

where,

$$h(\cdot)\alpha_i(\cdot)(r(\cdot)+1) = \frac{p_i(\cdot)h(\cdot)(r(\cdot)+1)}{h(\cdot)+1} = \frac{Np_i(\cdot)(\bar{p}(\cdot)-1)(r(\cdot)+1)}{\bar{p}(\cdot)(N-1)}.$$

□

We need the following Lemma (see [22]) to prove the Lemma after it

Lemma 3.11 ([22]). *Let $v(\cdot), w(\cdot) \in C(\bar{\Omega})$, such that $w^- > 0, (v-w)^- > 0$.*

If $u \in \mathcal{M}^{v(\cdot)}(\Omega)$, then $|u|^{w(\cdot)} \in L^1(\Omega)$.

In addition to that, $\mathcal{M}^{v(\cdot)}(\Omega) \subset L^{w(\cdot)}(\Omega)$ for all $v(\cdot), w(\cdot) \geq 1$.

Lemma 3.12. *Let f, g and $p_i, \sigma_i, i = 1, \dots, N$ be restricted as in Theorem 3.2. Then, for all $i = 1, \dots, N$,*

$$u_n \text{ is bounded in } L^{q_i(x)}(\Omega), \quad (3.29)$$

$$\partial_i u_n \text{ is bounded in } L^{q_i(x)}(\Omega), \quad (3.30)$$

where $q_i(\cdot), i = 1, \dots, N$ satisfying (3.3).

Proof. From (3.24), thanks to Lemma 3.11, we deduce that

$$\partial_i(K(|u_n|)) \text{ is bounded in } L^{h_i(\cdot)}(\Omega), \quad i = 1, \dots, N, \quad (3.31)$$

where, $1 < h_i(\cdot) < \frac{Np_i(\cdot)(\bar{p}(\cdot)-1)}{\bar{p}(\cdot)(N-1)}, i = 1, \dots, N$.

So, we can obtain

$$K(|u_n|) \text{ is bounded in } L^{h_i(\cdot)}(\Omega), \quad i = 1, \dots, N, \quad (3.32)$$

where, $1 < h_i(\cdot) < \frac{Np_i(\cdot)(\bar{p}(\cdot)-1)}{\bar{p}(\cdot)(N-1)}, i = 1, \dots, N$.

By condition (1.5) we can get

$$C |K(|u_n|)| \geq |u_n|^{r(\cdot)+1}, \quad |u_n| \geq \lambda, \quad i = 1, \dots, N. \quad (3.33)$$

Then, through (3.33) and (3.32) we obtain

$$\begin{aligned} \int_{\Omega} |u_n|^{h_i(\cdot)(r(\cdot)+1)} dx &= \int_{\{|u_n| \geq \lambda\}} |u_n|^{h_i(\cdot)(r(\cdot)+1)} dx \\ &\quad + \int_{\{|u_n| < \lambda\}} |u_n|^{h_i(\cdot)(r(\cdot)+1)} dx \\ &\leq c \int_{\Omega} |K(|u_n|)|^{h_i(\cdot)} dx + (1 + \lambda^{h_i^+(\cdot)(r_+^++1)}) |\Omega| \leq C. \end{aligned} \quad (3.34)$$

Then, (3.34) implies that, for all $i = 1, \dots, N$

$$u_n \in L^{q_i(\cdot)}(\Omega), \quad (3.35)$$

where, $q_i(\cdot), i = 1, \dots, N$ satisfying (3.3).

From (2.2) and (3.35) we deduce (3.29).

Finally, by (3.25), Lemma 3.11, and (2.2), we can get (3.30). □

Remark 3.13. Lemma 3.12 implies that

$$u_n \text{ is bounded in } W_0^{1, \vec{q}(\cdot)}(\Omega), \quad (3.36)$$

where, $\vec{q}(\cdot) = (q_1(\cdot), \dots, q_N(\cdot))$, such that $q_i(\cdot)$, $i = 1, \dots, N$ satisfying (3.3).

Lemma 3.14. For all $i = 1, \dots, N$

$$\lim_{n \rightarrow +\infty} \Delta_{i,n} = 0, \quad (3.37)$$

where,

$$\Delta_{i,n} = \int_{\Omega} (\sigma_i(x, T_n(u_n), \partial_i u_n) - \sigma_i(x, T_n(u_n), \partial_i u)) (\partial_i u_n - \partial_i u) dx.$$

Proof. From (3.36), we can conclude that the sequence (u_n) is bounded in

$$W_0^{1, q^-}(\Omega), \text{ where } q^- = \min_{1 \leq i \leq N} \min_{x \in \overline{\Omega}} q_i(x).$$

So, a sequence (still denoted by (u_n)) can be extracted from them, such that

$$u_n \longrightarrow u \quad \text{strongly in } W_0^{1, q^-}(\Omega) \text{ and a.e in } \Omega, \quad (3.38)$$

$$\text{and, } \partial_i u_n \rightharpoonup \partial_i u \text{ weakly in } L^{p_i(x)}(\Omega), \quad i = 1, \dots, N. \quad (3.39)$$

Note that, for all $i = 1, \dots, N$,

$$\Delta_{i,n} = \Delta_{i,n}^{(1)} - \Delta_{i,n}^{(2)}$$

where

$$\begin{aligned} \Delta_{i,n}^{(1)} &= \int_{\Omega} \sigma_i(x, T_n(u_n), \partial_i u_n) (\partial_i u_n - \partial_i u) dx \\ \Delta_{i,n}^{(2)} &= \int_{\Omega} \sigma_i(x, T_n(u_n), \partial_i u) (\partial_i u_n - \partial_i u) dx. \end{aligned}$$

First, let's prove for all $i = 1, \dots, N$

$$\lim_{n \rightarrow +\infty} \Delta_{i,n}^{(1)} = 0. \quad (3.40)$$

Choose $\varphi = u_n - u$ as a test function in (3.7), we get

$$\begin{aligned} &\sum_{i=1}^N \int_{\Omega} \sigma_i(x, T_n(u_n), \partial_i u_n) (\partial_i u_n - \partial_i u) dx \\ &\quad + \int_{\Omega} g(x, u_n) (u_n - u) dx = \int_{\Omega} f_n(u_n - u) dx. \end{aligned} \quad (3.41)$$

By using (1.9), and that $u_n \in L^{p_i(\cdot)}(\Omega)$, $i = 1, \dots, N$, we can get

$$\int_{\Omega} |g(x, u_n)|^{p'_i(x)} dx \leq \int_{\Omega} |u_n|^{p_i(x)} dx \leq c, \quad (3.42)$$

then (3.42) implies that,

$$(g(x, u_n)) \text{ is bounded in } L^{p'_i(\cdot)}(\Omega). \quad (3.43)$$

So, from (3.43), and (3.38), we get

$$\lim_{n \rightarrow +\infty} \int_{\Omega} g(x, u_n)(u_n - u) dx = 0. \quad (3.44)$$

Now, by (1.2), Young's inequality, and that $\partial_i u_n, K(T_n(u_n)) \in L^{p_i(\cdot)}(\Omega)$, $i = 1, \dots, N$, we deduce that

$$\begin{aligned} \int_{\Omega} |\sigma_i(x, T_n(u_n), \partial_i u_n)|^{p'_i(\cdot)} dx &\leq c \int_{\Omega} |K(T_n(u_n))|^{p_i(x)} dx \\ &\quad + c' \int_{\Omega} |\partial_i u_n|^{p_i(x)} dx + c'' \leq C, \end{aligned}$$

and this implies the boundedness of $(\sigma_i(x, T_n(u_n), \partial_i u_n))$ in $L^{p'_i(\cdot)}(\Omega)$. Thanks to this and (3.39) we get

$$\lim_{n \rightarrow +\infty} \int_{\Omega} \sigma_i(x, T_n(u_n), \partial_i u_n)(\partial_i u_n - \partial_i u) dx = 0. \quad (3.45)$$

Then, from (3.38), (3.44), (3.45), and (3.5), we get (3.40).

Now, from (1.2), and that $\partial_i u \in L^{p_i(\cdot)}$, we obtain for all $i = 1, \dots, N$

$$\int_{\Omega} |\sigma_i(x, T_n(u_n), \partial_i u)|^{p'_i(\cdot)} dx \leq c \int_{\Omega} |\partial_i u|^{p_i(x)} dx + c' \leq C.$$

And therefore

$$(\sigma_i(x, T_n(u_n), \partial_i u)) \text{ is bounded in } L^{p'_i(\cdot)}(\Omega), \quad i = 1, \dots, N. \quad (3.46)$$

Then, (3.46) and (3.39) implies that

$$\lim_{n \rightarrow +\infty} \Delta_{i,n}^{(2)} = 0. \quad (3.47)$$

So, by (3.40) and (3.47), we derive (3.37). $\square$

Lemma 3.15. *For all $i = 1, \dots, N$*

$$\partial_i u_n \longrightarrow \partial_i u, \quad \text{a.e. in } \overline{\Omega}. \quad (3.48)$$

Proof. Through (1.4) we conclude that, for all $i = 1, \dots, N$

$$(\sigma_i(x, T_n(u_n), \partial_i u_n) - \sigma_i(x, T_n(u_n), \partial_i u))(\partial_i u_n - \partial_i u) > 0. \quad (3.49)$$

Then, (3.49) and (3.37) gives us, for all $i = 1, \dots, N$

$$(\sigma_i(x, T_n(u_n), \partial_i u_n) - \sigma_i(x, T_n(u_n), \partial_i u))(\partial_i u_n - \partial_i u) \longrightarrow 0, \text{ strongly in } L^1(\Omega). \quad (3.50)$$

Extracting a subsequence (still denoted by (u_n)), we have for all $i = 1, \dots, N$

$$(\sigma_i(x, T_n(u_n), \partial_i u_n) - \sigma_i(x, T_n(u_n), \partial_i u))(\partial_i u_n - \partial_i u) \longrightarrow 0 \quad \text{a.e. in } \Omega. \quad (3.51)$$

Then, by the same techniques used in [11, 8] we can obtain (3.48). $\square$

3.2. Proof of the Theorem 3.2 :

By (3.38), we have

$$g(x, u_n) \longrightarrow g(x, u) \quad \text{a.e. in } \Omega. \quad (3.52)$$

Let $E \subset \Omega$ be any measurable set, we write

$$\int_E |g(x, u_n)| \, dx = \int_{E \cap \{|u_n| \leq t\}} |g(x, u_n)| \, dx + \int_{E \cap \{|u_n| > t\}} |g(x, u_n)| \, dx.$$

Let $0 < M < t$, and observe that

$$|T_t(u_n)| \leq |T_t(u_n)| \mathbf{1}_{\{|u_n| \leq M\}} + |T_t(u_n)| \mathbf{1}_{\{|u_n| > M\}} \leq M + t \mathbf{1}_{\{|u_n| > M\}}. \quad (3.53)$$

Then, after taking $\varphi = T_t(u_n)$ in (3.7) and using (3.53), yields

$$t \int_{\{|u_n| > t\}} |g(x, u_n)| \, dx \leq M \int_{\Omega} |f_n| \, dx + t \int_{\{|u_n| > M\}} |f_n| \, dx. \quad (3.54)$$

From (3.54) and (3.11), we conclude the equi-integrability of $g(x, u_n)$ in $L^1(\Omega)$. Through this, (3.52), and Vitali's theorem we get

$$g(x, u_n) \longrightarrow g(x, u) \quad \text{strongly in } L^1(\Omega). \quad (3.55)$$

From (3.29) and (3.48), we have

$$\sigma_i(x, T_n(u_n), \partial_i u_n) \longrightarrow \sigma_i(x, u, \partial_i u) \quad \text{a.e. in } \Omega. \quad (3.56)$$

Now, we prove that

$$\sigma_i(x, T_n(u_n), \partial_i u_n) \longrightarrow \sigma_i(x, u, \partial_i u) \quad \text{strongly in } L^{\frac{q_i(\cdot)}{p_i(\cdot)-1}}(\Omega),$$

where $q_i(\cdot)$, $i = 1, \dots, N$ are continuous functions on $\overline{\Omega}$ satisfying (3.3). Then, we have, for all $x \in \overline{\Omega}$

$$1 < \frac{q_i(x)}{p_i(x) - 1} < \frac{N(\overline{p}(x) - 1)p_i(x)(r(x) + 1)}{\overline{p}(x)(N - 1)(p_i(x) - 1)}, \quad i = 1, \dots, N. \quad (3.57)$$

The choice of $\frac{q_i(x)}{p_i(x) - 1} > 1$ is possible since we have (3.4).

Using (1.2), and (3.30), we get that,

$$\int_{\Omega} |\sigma_i(x, T_n(u_n), \partial_i u_n)|^{\frac{q_i(x)}{p_i(x) - 1}} \, dx \leq c \int_{\Omega} |\partial_i u_n|^{q_i(x)} + C \, dx \leq C', \quad i = 1, \dots, N. \quad (3.58)$$

Then, by (3.58) and using (2.2), we conclude that, for all $i = 1, \dots, N$,

$$(\sigma_i(x, T_n(u_n), \partial_i u_n)) \quad \text{uniformly bounded in } L^{\frac{q_i(\cdot)}{p_i(\cdot)-1}}(\Omega).$$

So, by (3.56) and Vitali's theorem, we derive, for all $i = 1, \dots, N$,

$$\sigma_i(x, T_n(u_n), \partial_i u_n) \longrightarrow \sigma_i(x, u, \partial_i u) \quad \text{strongly in } L^1(\Omega). \quad (3.59)$$

So, by passing to the limit in (3.7), we have completed the proof.

References

- [1] Almeida, A., Harjulehto, P., Hästö, P., Lukkari, T., *Riesz and Wolff potentials and elliptic equations in variable exponent weak Lebesgue spaces*, Ann. Mat. Pura. Appl., **194**(2015), 405–424.
- [2] Bendahmane, M., Karlsen, KH., *Anisotropic nonlinear elliptic systems with measure data and anisotropic harmonic maps into spheres*, Electron. J. Differ. Equ., **46**(2006), 1–30.
- [3] Chen, Y., Levine, S., Rao, M., *Variable exponent, linear growth functionals in image restoration*, SIAM J. Appl. Math., **66**(2006), 1383–1406.
- [4] Cruz-Uribe, D., Fiorenza, A., Ruzhansky, M., Wirth, J., *Variable Lebesgue Spaces and Hyperbolic Systems*. Advanced Courses in Mathematics- CRM Barcelona. Birkhäuser, Basel, 2014.
- [5] Diening, L., Harjulehto, P., Hästö, P., Ruzicka, M., *Lebesgue and Sobolev Spaces with Variable Exponents*, Lecture Notes in Mathematics, Springer. vol. 2017, New York (2011).
- [6] Fan, X., Zhao, D., *On the spaces $L^{p(x)}(\Omega)$ and $W^{1,p(x)}(\Omega)$* , J. Math. Anal. Appl., **263**(2001), 424–446.
- [7] Fan, X., *Anisotropic variable exponent Sobolev spaces and $\vec{p}(x)$ -Laplacian equations*, Complex Var. Elliptic Equ., **56**(2011), 623–642.
- [8] Lions, J. L., *Quelques méthodes de résolution des problèmes aux limites*, Dunod, Paris, 1969.
- [9] Mihailescu, M., Radulescu, V., *A multiplicity result for a nonlinear degenerate problem arising in the theory of electrorheological fluids*, Proc. R. Soc. A., **462**(2006), 2625–2641.
- [10] Naceri, M., *Existence results for anisotropic nonlinear weighted elliptic equations with variable exponents and L^1 data*, Proc. Rom. Acad. Ser. A Math. Phys. Tech. Sci. Inf. Sci., **23**(4), pp. 337–346, 2022.
- [11] Naceri, M., Mokhtari, F., *Anisotropic nonlinear elliptic systems with variable exponents and degenerate coercivity*, Appl. Anal., **100**(11)(2021), 2347–2367.
- [12] Naceri, M., Benboubker, M. B., *Distributional solutions of anisotropic nonlinear elliptic systems with variable exponents: existence and regularity*, Adv. Oper. Theory., **7**(2)(2022), 1–34 .
- [13] Naceri, M., *Anisotropic nonlinear elliptic systems with variable exponents, degenerate coercivity and $L^q(\cdot)$ data*, Ann. Acad. Rom. Sci. Ser. Math. Appl., **14**(1-2)(2022), 107–140.
- [14] Naceri, M., *Anisotropic nonlinear weighted elliptic equations with variable exponents* , Georgian Math. J., vol. **30**, no. 2, 2023, pp. 277–285.
- [15] Naceri, M., *Anisotropic nonlinear elliptic equations with variable exponents and two weighted first order terms*, Filomat, **38**(3)(2024), 1043–1054.
- [16] Naceri, M., *Nonlinear Elliptic Equations with Variable Exponents Anisotropic Sobolev Weights and Natural Growth Terms*, Tatra Mt. Math. Publ., **88**(2024), 109–126.
- [17] Naceri, M., *Entropy solutions for variable exponents nonlinear anisotropic elliptic equations with natural growth terms*, Rev. Colombiana Mat., Vol. **58** No. 1 (2024), 99–115.
- [18] Naceri, M., *Singular Anisotropic Elliptic Problems with Variable Exponents*, Mem. Differ. Equ. Math. Phys., **85**(8)(2022), 119 –132 .

- [19] Naceri, M., *Variable exponents anisotropic nonlinear elliptic systems with $L^{\vec{p}'(\cdot)}$ -data*. Appl. Anal., **104**(3), 564–581(2024).
- [20] Naceri, M., *Existence results for an nonlinear variable exponents anisotropic elliptic problems*, Kyungpook Math. J., **64**(2024), no. 2, 271–286.
- [21] Ružička, M., *Electrorheological fluids: modeling and mathematical theory*, Springer, Berlin. Lecture Notes in Mathematics, **1748**(2000).
- [22] Sanchón, M., Urbano, M., *Entropy solutions for the $p(x)$ -Laplace equation*, Trans. Amer. Math. Soc., **361**(2009), 6387–6405.

Mokhtar Naceri 

Mathematics Department, ENS of Laghouat, Box 4033 Station Post, Avenue of Martyrs, 03000, Laghouat, Algeria.

Applied Chemical and Physical Sciences Laboratory, ENS of Laghouat, 03000, Laghouat, Algeria.

e-mail: nasrimokhtar@gmail.com, m.naceri@ens-lagh.dz